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About one inverse problem in pharmacokinetics

Dimitar Vandev¹ and Krasimira Prodanova²



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About one inverse problem in pharmacokinetics

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About one inverse problem in pharmacokinetics

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1. Introduction

- The body is assumed as a control system. The transit times of the drug molecules are considered as i.i.d. random variables.

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1. Introduction

- The body is assumed as a control system. The transit times of the drug molecules are considered as i.i.d. random variables.
- The density function $F(t)$ of transit times characterizes the body with respect to the transport of drug, i.e. $F(t)$ determines the transport function of the control system.

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1. Introduction

- The body is assumed as a control system. The transit times of the drug molecules are considered as i.i.d. random variables.
- The density function $F(t)$ of transit times characterizes the body with respect to the transport of drug, i.e. $F(t)$ determines the transport function of the control system.
- The output, i.e. the time course of the plasma concentration $C(t)$ at the exit is the result of dosage flow (input) $G(t)$ and the transport function $F(t)$:

$$C(t) = \int_0^t G(\tau)F(t - \tau)d\tau. \quad (1)$$



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2. Compartment models

If a dose of drug is applied to the body by means of a bolus injection, the input $G(t)$ may be considered as a δ -impulse and all molecules enter that system (body) at the same time. They leave the body according to the distribution of transit times.



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The function $F(t)$ then can be derived by application of classic compartment modeling to the experimental plasma concentration after intravenous (i.v) input.



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The function $F(t)$ then can be derived by application of classic compartment modeling to the experimental plasma concentration after intravenous (i.v) input. The data points can be fitted to sum of exponents:

$$C^{i.v.}(t) = \sum_{i=1}^n A_i e^{-\alpha_i t}, \quad (2)$$

where n is the number of compartments, $C^{i.v.}(t)$ represents the plasma concentration at time t . A_i and α_i are positive constants, which characterize the drug kinetic 1).



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Time	C	Delta
0.02	6.16	1.83
0.05	4.01	1.49
0.08	3.36	0.76
0.17	2.96	1.16
0.33	2.26	0.6
0.67	1.47	0.55
1	0.63	0.13
2	0.32	0.006

Table 1: Intravenous application
of EMOVIT

Concentrations measured in the blood
after intravenous application of the
drug to 10 patients.

In the third column the standard
deviations of the measurements are
presented.



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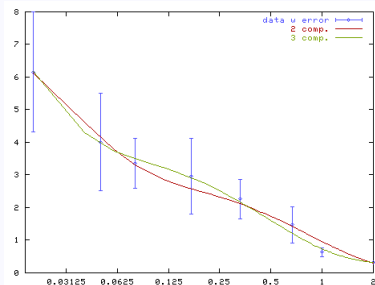


Figure 1: Estimated observation using compartment models

On the picture we see the observed plasma concentrations and estimated transport function using 2- and 3- compartment models. The time is on logarithmic scale.

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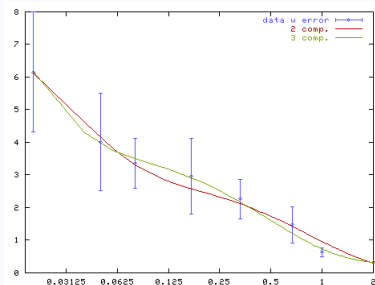


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The choice of simpler 2-compartment model was made using F-test.

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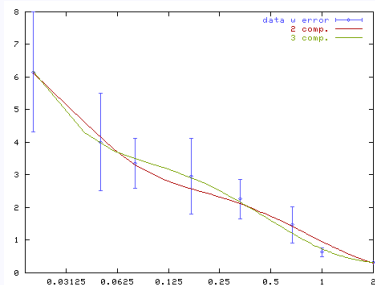


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The values of estimated parameters:

$$\begin{aligned} A_1 &= 5.74 & A_2 &= 3.12 \\ \alpha_1 &= 31.28 & \alpha_2 &= 1.17 \end{aligned}$$

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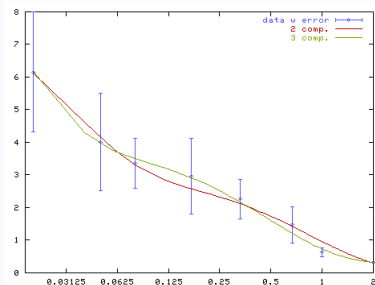


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$$A_1 = 5.74 \quad A_2 = 3.12$$

$$\alpha_1 = 31.28 \quad \alpha_2 = 1.17$$

Therefore, the output concentration $C^{i.v.}(t)$ is directly proportional to the density function $F(t)$ of the transit times:

$$F(t) = \frac{C^{i.v.}(t)}{\int_0^{\infty} C^{i.v.}(t) dt} = \frac{C^{i.v.}(t)}{\sum_{i=1}^n \frac{A_i}{\alpha_i}}. \quad (3)$$



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3. The Problem of Unknown Input

When the application of the drug is non intravenous (i.e. is oral, muscular, subcutaneous etc.), the input function $G(t)$ (absorption process) is unknown.



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Time	C	Delta
0	0	0.0
0.08	1.441	1.475
0.33	1.873	0.782
0.5	2.333	0.948
1.0	2.23	0.514
1.5	1.777	0.744
2.0	1.48	0.879
3.0	0.607	0.298
6.0	0.1	0.1

Concentrations measured in the blood after oral application of the drug to the same 10 patients.

Table 2: Oral application of EMOVIT



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Table 2: Oral application of EMOVIT

Concentrations measured in the blood after oral application of the drug to the same 10 patients.

In the third column the standard deviations of the measurements are presented. They are too big.



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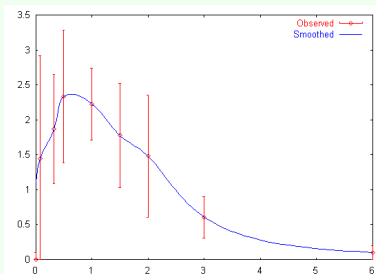


Figure 2: Smothed oral data

The problem is to estimate the input function $G(t)$ by given:



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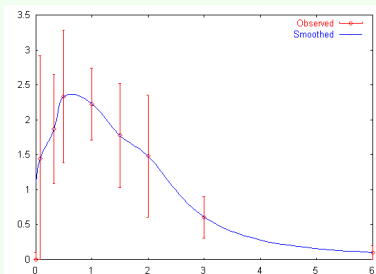


Figure 2: Smothed oral data

The problem is to estimate the input function $G(t)$ by given:

- N data points of plasma concentration $C_i = C^{noni.v.}(t)$, ($i = 1, 2, \dots, N$), determined experimentally as an average value after oral application of the drug to 10 individuals in the moment t_i ;



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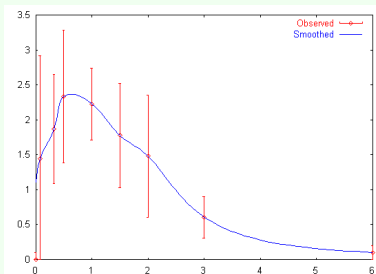


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- the standard deviation δ of the individual measurement;



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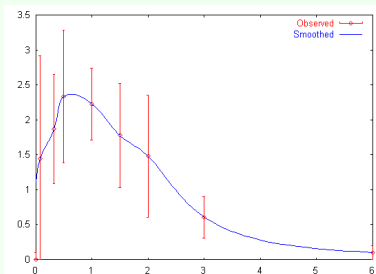


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- the standard deviation δ of the individual measurement;
- estimated from (3) body transport function $F(t)$.



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4. Splines

For solving equation 1 an appropriate deconvolution procedure is employed. The function $G(t)$ is sought in the form of cubic spline with $m + 1$ knots ($m \leq N$):

$$G_i(\tau) = G_i^0 + G_i^1 (\tau - T_{j-1}) + G_i^2 (\tau - T_{j-1})^2 + G_i^3 (\tau - T_{j-1})^3,$$



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where $j=1,2,\dots,m$, $T_j \in [0, t_N]$ are knots, $\tau \in [T_{j-1}, T_j]$ and G_j^s , $s = 0, 1, 2, 3$ are unknown spline coefficients.



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$$\begin{cases} G_{j-1}(T_j) = G_j(T_j), \\ G'_{j-1}(T_j) = G'_j(T_j), \\ G''_{j-1}(T_j) = G''_j(T_j), \end{cases}$$



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$$\begin{cases} G_{j-1}(T_j) = G_j(T_j), \\ G'_{j-1}(T_j) = G'_j(T_j), \\ G''_{j-1}(T_j) = G''_j(T_j), \end{cases} \quad (5)$$

where $j=2,\dots,m$ and $G_1(0) = G'_1(0) = 0$.



Then for every $t_i \in [T_{l-1}, T_l]$, $i = 1, 2, \dots, N$, $l = 1, 2, \dots, m$ from (1) and (4) it follows:

$$C(t_i) = \sum_{j=1}^{i-1} \sum_{s=0}^3 G_j^s \int_{T_{j-1}}^{T_j} (\tau - T_j)^s F(t_i - \tau) d\tau \\ + \sum_{s=0}^3 G_l^s \int_{T_{l-1}}^{t_i} (\tau - T_{l-1})^s F(t_i - \tau) d\tau.$$

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Obviously (6) represents a linear system of N equations with $4m$ unknown quantities $g_1 = G_1^0$, $g_2 = G_1^1$, $g_3 = G_1^2$, $g_4 = G_1^3$, $g_5 = G_2^0$, ..., $g_{4m} = G_m^3$:

$$XG = C,$$



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Obviously (6) represents a linear system of N equations with $4m$ unknown quantities $g_1 = G_1^0$, $g_2 = G_1^1$, $g_3 = G_1^2$, $g_4 = G_1^3$, $g_5 = G_2^0$, ..., $g_{4m} = G_m^3$:

$$XG = C, \quad (7)$$

where X is the matrix of coefficients calculated from (6) by exact computation the integrals, $G = (g_1, g_2, \dots, g_{4m})'$, $C = (C_1, C_2, \dots, C_N)'$, ($\{ '\}$ - transpose of a matrix).



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The conditions (5) in a matrix form could be written as

$$AG = 0, \quad (8)$$

where A is $3(m - 1) \times 4m$ dimensional matrix.



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For finding the unknown spline coefficients of G , the least square estimation (2) is used. They are obtained by the conditions for minimizing the functional

$$\Phi = (C - XG)' W (C - XG), \quad (9)$$

where $W = DRD$ is $N \times N$ dimensional matrix, D is a diagonal matrix, which elements are δ_i and R is correlation matrix of data vector C .



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After minimization of (9) it follows that

$$G = (X'W^{-1}X + A'A)^{-1} X'W^{-1}C. \quad (10)$$

5. Simulation

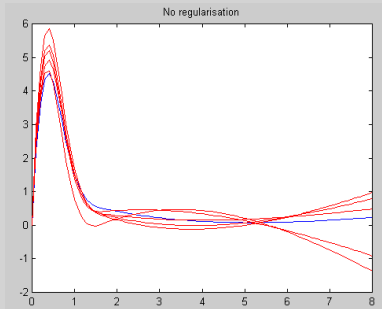


Figure 3: No regularization

Let the experimental data are perturbed

$$Y_{(p)} = C + \theta_p \delta, \quad (p = 1, 2, \dots),$$

where $\delta = (\delta_1, \delta_2, \dots, \delta_N)'$ and θ_p are random numbers $|\theta_p| \leq 1$.



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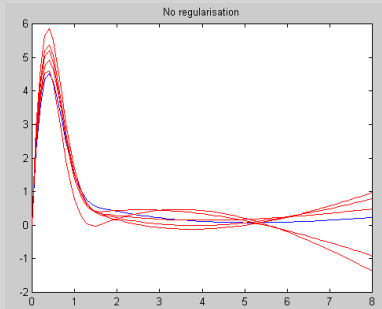
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5. Simulation



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Figure 3: No regularization

The solutions $G_{(p)}$ of (10), where now C is $Y_{(p)}$, show instability I in the sense of Tikhonov 3).



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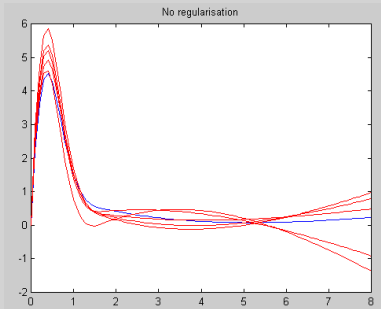
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Let the experimental data are perturbed

$$Y_{(p)} = C + \theta_p \delta, \quad (p = 1, 2, \dots),$$

where $\delta = (\delta_1, \delta_2, \dots, \delta_N)'$ and θ_p are random numbers $|\theta_p| \leq 1$.

Figure 3: No regularization

The solutions $G_{(p)}$ of (10), where now C is $Y_{(p)}$, show instability I in the sense of Tikhonov (3).

On Fig. 3 the right side of (1) with perturbations ($p = 5$) and solutions $G_{(p)}$ are presented.

The estimated data points C_i with δ_i are from plasma concentrations after oral application of psycho therapeutic drug EMOVIT.



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6. Stabilization

For finding the generalized solution of (1) (quasi-solution 3)), which is stable with respect to small perturbation of the right side of (1), the following algorithm is proposed.

(12)



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6. Stabilization

For finding the generalized solution of (1) (quasi-solution 3)), which is stable with respect to small perturbation of the right side of (1), the following algorithm is proposed.

The functional

$$M^\alpha[G] = \Phi + \alpha\Omega(G) \quad (11)$$

is introduced, where $\alpha > 0$ is parameter of regularization, $\Omega(G)$ is appropriate chosen stabilizing functional. The function $G(t)$ is sought by the condition of minimizing the functional (11)

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$$G^\alpha = (X'W^{-1}X + A'A + \alpha\Omega)^{-1} X'W^{-1}C. \quad (12)$$



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In the concrete case Ω has the form

$$\Omega(G) = \int_{\beta}^{t_N} [G''(\tau)]^2 d\tau, \quad (13)$$

where $\beta \in [0, t_N]$ is a parameter, which controls the smoothing of the splines (4).



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where $\beta \in [0, t_N]$ is a parameter, which controls the smoothing of the splines (4). For fixed $T_{j-1} \leq \beta \leq T_j$ ($j = 1, 2, \dots, m$), (13) obtains the form

$$\Omega(G) = \sum_{q=j}^m \left[4 (G_q^2)^2 \Delta_q + 12 G_q^2 G_q^3 (\Delta_q)^2 + 12 (G_q^3)^2 (\Delta_q)^3 \right], \quad (14)$$

where $\Delta_q = T_q - T_{q-1}$.

The quantity of α is determined according suggestion in 3) by using the error estimation

$$\varepsilon = \frac{1}{N} \sqrt{\sum_{i=1}^N \delta_i^2}$$



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The quantity of α is determined according suggestion in 3) by using the error estimation

$$\varepsilon = \frac{1}{N} \sqrt{\sum_{i=1}^N \delta_i^2}$$

as follows

$$\rho = (XG^\alpha, C) = \varepsilon,$$

where ρ is the distance of Mahalanobis 4):

$$\rho(U, V) = [(U - V)'(U - V)]^{\frac{1}{2}}.$$



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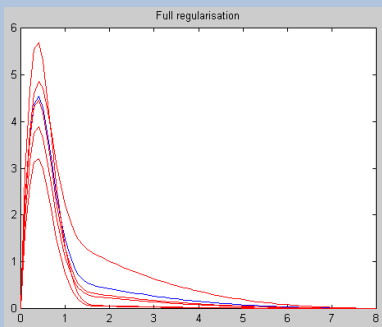


Fig.4 shows the stabilized quasi-solution G^α , obtained for $\alpha = 0.06$ and $\beta = 0.89$ from experimental data of EMOVIT.

Figure 4: Full regularization

The proposed method offers better and more stimulating information about the drug absorption process, which is not observable and therefore shows some new ways in pharmacokinetical investigations.



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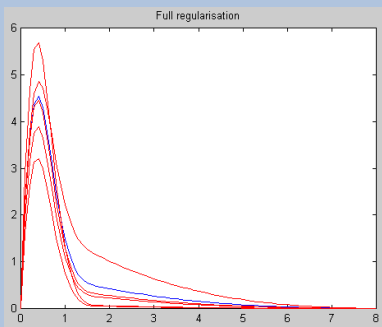


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